

Rubin Observatory

Vera C. Rubin Observatory
Systems Engineering

Integration Milestones

Robert Lupton

SITCOMTN-006

Latest Revision: 2020-09-10



Abstract

A proposal for ways to work on predominantly software subsystem commissioning, building on the RAT (née auxTel) experience

Change Record

Version	Date	Description	Owner name
1	YYYY-MM-DD	Unreleased.	Robert Lupton

Document source location: <https://github.com/lsst-sitcom/sitcomtn-006>

Contents

1 Introduction	1
2 IM0: the Rubin Auxiliary Telescope (RAT)	1
2.1 Lessons Learned	1
3 IM1	2
A References	3
B Acronyms	3

Integration Milestones

1 Introduction

The Rubin construction project is composed of three main subsystems: DM, Camera, and T&S.¹ but in operations there is only one survey. The task of merging the projects is not easy, especially when some of the interfaces are underspecified, or turn out to need modification based on experience. This is primarily a problem for the software — the hardware interfaces, specified in mm and screw threads, are generally well defined.

Once we accept that the only way to complete the integration of the subsystems is to actually integrate them, while expecting that the interfaces and requirements will evolve, we recognise that our situation is analogous to the way that software development has moved from waterfall to agile development models.

This technote proposes that we introduce the concept of an Integration Milestone (IM) which defines a specified set of functionalities that are available to the Rubin project. This is slightly different from DM's current Operation Rehearsal (OR) concept which tests the state of DM systems at a certain time rather than guaranteeing continued cross-subsystem functionality. I envisage that an IM would be followed by an OR to test the deliverable, and to carry out an internal Operations Readiness Review (ORR) for the functionality delivered by the IM.

2 IM0: the RAT

Add discussion of the work required to get the auxTel working

2.1 Lessons Learned

Discuss *e.g.* OCS-CCS integration.

¹And also EPO, but this is not relevant here.

3 IM1

My proposed first IM would be to integrate comCam in La Serena. This means:

- running comCam reliably in Chile
 - without logging into CCS machines
 - integrating camera-side monitoring into Rubin operations
 - writing files the way that we plan to in operations (i.e. directly from CCS)
 - taking data using the OCS
 - writing telemetry to the EFD
 - using a logging system (which Frossie is designing for SITCOM); no use of e.g. eTraveller
 - using the script queue
 - * In particular calibration sets: bias, dark, flat, PTC
 - using LOVE to see monitor operations
 - using OCPS (OCS driven Data Processing; DMTN-133) to process data in Chile
 - * need to understand interaction with the diagnostic cluster
 - with a nublado instance in Chile to allow ad-hoc analysis
 - transferring data to NCSA and ingesting with a few-second latency and 100% reliability, or at least logging
 - mirroring or copying the EFD
 - automatically processing suitable data as it arrives
 - presumably using gen3
 - N.b. will require us to establish conventions on “suitable data”
 - running automated calibration scripts
 - including QA
 - doing something with the results of the QA
 - using the RSP to look at data
-

- including EFD access
- and a decently-high up time and performance.
- things I haven't thought of yet

Quite a lot of this doesn't exist, and may have to be moved out to a later IM depending on resource availability. I suspect there'll be push-back on some of this because doing things this way isn't the way that it was planned (or really not planned, but written down in silos). In some cases this will be reasonable, for example we may decide that some fraction of CCS configuration is indeed better carried out by logging into CCS nodes.

A References

B Acronyms

Acronym	Description
AURA	Association of Universities for Research in Astronomy
CCS	Camera Control System
DM	Data Management
DMS	Data Management Subsystem
DMTN	DM Technical Note
DOE	Department of Energy
EFD	Engineering and Facility Database
EPO	Education and Public Outreach
IM	Integration Milestone
LDM	LSST Data Management (Document Handle)
LOVE	LSST Operations Visualization Environment
LSST	Legacy Survey of Space and Time (formerly Large Synoptic Survey Telescope)
MREFC	Major Research Equipment and Facility Construction
NCSA	National Center for Supercomputing Applications

NOAO	National Optical Astronomy Observatories (USA)
NSF	National Science Foundation
OCS	Observatory Control System
OR	Operation Rehearsal
ORR	Operations Readiness Review
QA	Quality Assurance
QC	Quality Control
RAT	Rubin Auxiliary Telescope
RSP	Rubin Science Platform
SE	System Engineering
SLAC	SLAC National Accelerator Laboratory (formerly Stanford Linear Accelerator Center; SLAC is now no longer an acronym)
T&S	Telescope and Site
US	United States